

Language

Level

Open & Examples

Save

Verify

Upload

Serial

Settings About



EN ▼



1 ▼



Otto move servo



USB PORT ▼



Logic

Loops

Variables

Functions

Math

▼ Arduino

In

Out

time

converting

serial communication

softserial lib

storage

Servo-Motor

read value on the analog input

the logic state of the digital pin

read value on the analog input

the logic state of the digital pin

the logic state of the digital pin

pull up

HIGH

toggle PIN state

angle 90°

1 time wait - push PIN#

1 Time wait - pull PIN#

Set Pin Mode for pin 0 to INPUT

random number between 0 and 100

to the transposed 0 over a range of [0-0]

constrain number from A = 0 to B = 100

attachInterrupt pin# 2 mode RISING

Setup

attach servomotor

id# SERVO

on the pin 2

Arduino loop forever:

rotate the servo-motor

SERVO

an angle (0~180°) of angle 90°

